

estimator for α_i and β_i , when the model has a single regressor X_i

THEORY OF PROBABILITY

8. Probability of the complementary event \bar{A} of A is given by

$$P(\bar{A}) = 1 - P(A)$$

A and \bar{A} are mutually disjoint events, so that



$$\Rightarrow P(A \cup \bar{A}) = P(S)$$

$$\Rightarrow P(A) + P(\bar{A}) = 1 \quad \left[\begin{array}{l} \text{from the axioms of} \\ \text{certainty and axioms of} \\ \text{additivity} \end{array} \right]$$

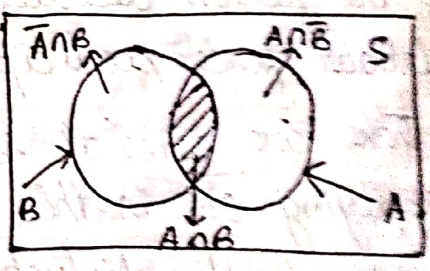
$$\Rightarrow P(\bar{A}) = 1 - P(A) \quad (\text{proved})$$

8. If A and B are any two events (subsets of sample space S) and are not mutually exclusive (disjoint) then,

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

From the venn diagram we have,

$$A \cup B = A \cup (\bar{A} \cap B)$$



where A and $\bar{A} \cap B$ are mutually exclusive or disjoint.

$$\therefore P(A \cup B) = P[A \cup (\bar{A} \cap B)]$$

$$= P(A) + P(\bar{A} \cap B) \quad \left[\begin{array}{l} \text{By the axiom of} \\ \text{additivity} \end{array} \right]$$

$$= P(A) + [P(\bar{A} \cap B) + P(A \cap B)] - P(A \cap B)$$

$$= P(A) + P[(\bar{A} \cap B) \cup (A \cap B)] - P(A \cap B) \quad \left[\begin{array}{l} \because \bar{A} \cap B \text{ and} \\ A \cap B \text{ are} \\ \text{disjoint} \end{array} \right]$$

$$= P(A) + P(B) - P(A \cap B)$$

\therefore we have, $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ (proved)

8. For two events, A and B,

$$P(A \cap B) = P(A) \cdot P(B|A) \cdot P(A) > 0$$

$$= P(B) \cdot P(A|B) \cdot P(B) > 0$$

where $P(B|A)$ represents conditional probability of occurrence of B when the event A has already happened, and $P(A|B)$ is the conditional probability of happening of A, given that B has already happened.

In usual notations, we have,

$$P(A) = \frac{n(A)}{n(S)}$$

where, $n(S)$ = no. of sample points in S

$n(A)$ = no. of sample points in A

$$P(B) = \frac{n(B)}{n(S)}$$

$n(B)$ = no. of sample points in B.

$$P(A \cap B) = \frac{n(A \cap B)}{n(S)}$$

$n(A \cap B)$ = no. of sample points in $(A \cap B)$

For the conditional event $(A|B)$, the favourable outcomes must be one of the sample points of B i.e. for the event $A|B$, the sample space is B and out of the $n(B)$ sample points $n(A \cap B)$ pertain to the occurrence of the event A. Hence,

$$P(A|B) = \frac{n(A \cap B)}{n(B)}$$

$$\therefore P(A \cap B) = \frac{n(B)}{n(S)} \times \frac{n(A \cap B)}{n(B)}$$

$$\Rightarrow P(A \cap B) = P(B) \cdot P(A|B) \quad \text{--- (1)}$$

$$\text{Similarly, } P(B|A) = \frac{n(A \cap B)}{n(A)}$$

$$\therefore P(A \cap B) = \frac{n(A)}{n(S)} \times \frac{n(A \cap B)}{n(A)}$$

$$\Rightarrow P(A \cap B) = P(A) \cdot P(B|A) \quad \text{--- (2)}$$

(1) and (2) gives the required result.

8. If A and B are two events with positive probabilities $\{P(A) > 0, P(B) > 0\}$, then A and B are independent if and only if, $P(A \cap B) = P(A) \cdot P(B)$.

We have,

$$P(A \cap B) = P(A) \cdot P(B/A) = P(B) \cdot P(A/B)$$

and $P(A) \neq 0, P(B) \neq 0$.

If A and B are independent i.e. A is independent of B and B is independent of A , then we have,

$$P(A/B) = P(A) \text{ and } P(B/A) = P(B).$$

Therefore,

$$P(A \cap B) = P(A) \cdot P(B). \text{ Hence, the theorem is proved.}$$

9. If X and Y are random variables then,

$$E(X+Y) = E(X) + E(Y)$$

provided all the expectations exist.

Let, X and Y be continuous random variables with joint p.d.f $f_{XY}(x, y)$ and marginal p.d.f's $f_X(x)$ and $f_Y(y)$ respectively. Then, by definition,

$$E(X) = \int_{-\infty}^{\infty} x \cdot f_X(x) \cdot dx \quad \text{--- (1)}$$

$$E(Y) = \int_{-\infty}^{\infty} y \cdot f_Y(y) \cdot dy \quad \text{--- (2)}$$

$$E(X+Y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x+y) \cdot f_{XY}(x, y) \cdot dx \cdot dy.$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x \cdot f_{XY}(x, y) \cdot dx \cdot dy + \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y \cdot f_{XY}(x, y) \cdot dx \cdot dy$$

$$= \int_{-\infty}^{\infty} x \left[\int_{-\infty}^{\infty} f_{XY}(x, y) \cdot dy \right] dx + \int_{-\infty}^{\infty} y \left[\int_{-\infty}^{\infty} f_{XY}(x, y) \cdot dx \right] dy$$

$$= \int_{-\infty}^{\infty} x \left[\int_{-\infty}^{\infty} f_X(x) \cdot f_Y(y) \cdot dy \right] dx$$

$$= \int_{-\infty}^{\infty} x \cdot f_x(x) \cdot dx + \int_{-\infty}^{\infty} y \cdot f_y(y) \cdot dy$$

$$= E(X) + E(Y) \quad \left[\text{By using (1) and (2) we get} \right]$$

$$\therefore E(X+Y) = E(X) + E(Y) \quad \text{Hence, it is proved.}$$

If X and Y are independent random variables, then,

$$E(XY) = E(X) \cdot E(Y)$$

Let X and Y be continuous random variables and independent with marginal p.d.f's $f_x(x)$ and $f_y(y)$ respectively. Then by definition,

$$E(X) = \int_{-\infty}^{\infty} x \cdot f_x(x) \cdot dx \quad (1)$$

$$E(Y) = \int_{-\infty}^{\infty} y \cdot f_y(y) \cdot dy$$

$$E(XY) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy \cdot f_{xy}(x, y) \cdot dx \cdot dy$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy \cdot f_x(x) \cdot f_y(y) \cdot dx \cdot dy \quad \left[\because X \text{ and } Y \text{ are independent random variables} \right]$$

$$= \int_{-\infty}^{\infty} x \cdot f_x(x) \cdot dx \int_{-\infty}^{\infty} y \cdot f_y(y) \cdot dy$$

$$= E(X) \cdot E(Y) \quad \left[\text{By using (1)} \right]$$

$$\therefore E(XY) = E(X) \cdot E(Y) \quad \text{Hence it is proved.}$$

Q. If x_1 and x_2 are random variables then,

$$(i) \text{Var} (ax_1 + bx_2) = a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) + 2ab \text{Cov} (x_1, x_2)$$

$$(ii) \text{Var} (ax_1 - bx_2) = a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) - 2ab \text{Cov} (x_1, x_2)$$

$$\text{Let, } u = ax_1 + bx_2$$

$$E(u) = a E(x_1) + b E(x_2)$$

$$\begin{aligned} \therefore u - E(u) &= ax_1 + bx_2 - a E(x_1) - b E(x_2) \\ &= a [x_1 - E(x_1)] + b [x_2 - E(x_2)] \end{aligned}$$

Squaring and taking expectation on both sides we get,

$$E [u - E(u)]^2 = E [a [x_1 - E(x_1)] + b [x_2 - E(x_2)]]^2$$

$$= E \left[a^2 \{x_1 - E(x_1)\}^2 + b^2 \{x_2 - E(x_2)\}^2 + 2ab \{x_1 - E(x_1)\} \{x_2 - E(x_2)\} \right]$$

$$= a^2 E [x_1 - E(x_1)]^2 + b^2 E [x_2 - E(x_2)]^2 + 2ab$$

$$E \left[\{x_1 - E(x_1)\} \{x_2 - E(x_2)\} \right]$$

$$= a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) + 2ab \text{Cov} (x_1, x_2)$$

$$\therefore \text{Var} (u) = a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) + 2ab \text{Cov} (x_1, x_2)$$

$$\therefore \text{Var} (ax_1 + bx_2) = a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) + 2ab \text{Cov} (x_1, x_2)$$

Similarly,

$$\text{Var} (ax_1 - bx_2) = a^2 \text{Var} (x_1) + b^2 \text{Var} (x_2) - 2ab \text{Cov} (x_1, x_2)$$

If $a = b = 1$ and x_1 and x_2 are independent random variables, then, $\text{Cov} (x_1, x_2) = 0$.

$$\text{Var} (x_1 \pm x_2) = \text{Var} (x_1) + \text{Var} (x_2)$$

$$\therefore \text{Var} (x_1) + \text{Var} (x_2) = \text{Var} (x_1 + x_2) = \text{Var} (x_1 - x_2)$$

8. Define moment generating function (m.g.f). How will you get the moments about origin and moments about mean from m.g.f.?

The moment generating function (m.g.f) of a random variable X (about origin) having the probability function $f(x)$ is given by.

$$M_X(t) = E[e^{tx}] = \begin{cases} \int e^{tx} f(x) \cdot dx & \text{(for continuous P.D)} \\ \sum_x e^{tx} f(x) \cdot dx & \text{(for discrete P.D)} \end{cases}$$

Thus,

$$M_X(t) = E[e^{tx}]$$

$$= E\left[1 + \frac{tx}{1!} + \frac{t^2 x^2}{2!} + \frac{t^3 x^3}{3!} + \frac{t^4 x^4}{4!} + \dots + \frac{t^r x^r}{r!} + \dots\right]$$

$$= 1 + t E(X) + \frac{t^2}{2!} E(X^2) + \frac{t^3}{3!} E(X^3) + \frac{t^4}{4!} E(X^4) + \dots + \frac{t^r}{r!} E(X^r)$$

$$= 1 + t \mu'_1 + \frac{t^2}{2!} \mu'_2 + \frac{t^3}{3!} \mu'_3 + \frac{t^4}{4!} \mu'_4 + \dots + \frac{t^r}{r!} \mu'_r + \dots$$

$$= \sum_{r=0}^{\infty} \frac{t^r}{r!} \mu'_r$$

where, $\mu'_r = E(X^r) = \begin{cases} \int x^r f(x) dx & \rightarrow \text{for continuous distribution} \\ \sum_x x^r p(x) & \rightarrow \text{for discrete distribution} \end{cases}$

is the r^{th} moment of X about origin. Thus, we see that the coefficient of $\frac{t^r}{r!}$ in $M_X(t)$ gives μ'_r (about origin). Since $M_X(t)$ generates moments, it is known as moment generating function.

Now, if we take the moment generating function of X about mean (\bar{x}) then we get,

$$M_{(X-\bar{x})}(t) = E[e^{t(X-\bar{x})}]$$

$$= E\left[1 + \frac{t(X-\bar{x})}{1!} + \frac{t^2(X-\bar{x})^2}{2!} + \frac{t^3(X-\bar{x})^3}{3!} + \frac{t^4(X-\bar{x})^4}{4!} + \dots + \frac{t^r(X-\bar{x})^r}{r!} + \dots\right]$$

$$= 1 + t E(x - \bar{x}) + \frac{t^2}{2!} E(x - \bar{x})^2 + \frac{t^3}{3!} E(x - \bar{x})^3 + \frac{t^4}{4!} E(x - \bar{x})^4 + \dots + \frac{t^n}{n!} E(x - \bar{x})^n + \dots$$

$$= 1 + 0 + \frac{t^2}{2!} \mu_2 + \frac{t^3}{3!} \mu_3 + \frac{t^4}{4!} \mu_4 + \dots + \frac{t^n}{n!} \mu_n + \dots$$

This is the moment generating function of x (about mean) which gives us the central moments.

9. State and explain the important properties of moment generating function (m.g.f).

The properties of m.g.f are discussed given below

(1) $M_{cx}(t) = M_x(ct)$. c being constant -

By definition,

$$\begin{aligned} \text{LHS} &= M_{cx}(t) \\ &= E(e^{tcx}) \end{aligned}$$

$$\text{RHS} = M_x(ct)$$

$$= E[e^{tcx}] = \text{LHS. (Proved)}$$

(2) The moment generating function of the sum of a number of independent random variables is equal to the product of their respective moment generating functions.

Symbolically, if x_1, x_2, \dots, x_n are independent random variables, then the moment generating function of their sum $(x_1 + x_2 + \dots + x_n)$ is given by,

$$M_{x_1 + x_2 + \dots + x_n}(t) = M_{x_1}(t) \cdot M_{x_2}(t) \cdot \dots \cdot M_{x_n}(t)$$

By definition,

$$\begin{aligned} M_{x_1 + x_2 + \dots + x_n}(t) &= E[e^{t(x_1 + x_2 + \dots + x_n)}] \\ &= E[e^{tx_1} \cdot e^{tx_2} \cdot \dots \cdot e^{tx_n}] \end{aligned}$$

$$= E[e^{tx_1}] \cdot E[e^{tx_2}] \cdot E[e^{tx_3}] \dots E[e^{tx_n}]$$

[$\because x_1, x_2, \dots, x_n$ are independent]

$$= M_{x_1}(t) \cdot M_{x_2}(t) \dots M_{x_n}(t)$$

$$\therefore M_{x_1+x_2+\dots+x_n}(t) = \prod_{i=1}^n M_{x_i}(t) \quad (\text{Proved})$$

(3) Effect of change of origin and scale on M.G.F.

Let us transform x to the new variable u by changing both the origin and scale in x as follows

$$u = \frac{x-a}{b} \quad \text{where } a \text{ and } b \text{ are constants.}$$

M.G.F of u (about origin) is given by.

$$\begin{aligned} M_u(t) &= E[e^{tu}] \\ &= E\left[e^{t\left(\frac{x-a}{b}\right)}\right] \\ &= E\left[e^{\frac{tx}{b} - \frac{at}{b}}\right] \\ &= e^{-at/b} \cdot E\left[e^{tx/b}\right] \\ &= e^{-at/b} \cdot M_x(t/b) \end{aligned}$$

where $M_x(t)$ is the m.g.f of x about origin.

In particular, if we take,

$$a = E(x) = \mu \text{ (say) and } b = \sigma_x = \sigma \text{ (say).}$$

then, $u = \frac{x - E(x)}{\sigma_x} = \frac{x - \mu}{\sigma} = z$ (say) is known as a standard variate.

Thus, the m.g.f of a standard variate z is given by,

$$M_X(t) = e^{-\mu t/\sigma} M_X(t/\sigma)$$

Hence, it is to be noted that,

$$E(Z) = E\left[\frac{X-\mu}{\sigma}\right] = \frac{1}{\sigma} E[X-\mu] = 0$$

$$\text{Var}(Z) = V\left[\frac{X-\mu}{\sigma}\right] = \frac{1}{\sigma^2} V(X-\mu) = \frac{\sigma^2}{\sigma^2} = 1$$

\therefore Mean and variance of a standard variate are zero and one.

(4) Uniqueness theorem of m.g.f — The m.g.f of a function of distribution, if it exists, uniquely determines the distribution. This implies that corresponding to a given probability distribution, there is only one m.g.f (provided it exists), and corresponding to a given m.g.f, there is only one probability distribution.

$$\text{Hence, } M_X(t) = M_Y(t)$$

\Rightarrow X and Y are identically distributed.